

In Fig. 1 we can see the «typical» SE DHT output stage. The purpose of pot, P1 (50 Ohms/2W typical) is to provide the way to «nulling» the hum. In Fig. 2 a,b,c, we can see other ways of connecting the filaments to cathode resistor Rk. We want potentiometer, to have some AC hum control, `cos we`ll use «traditional» 5V AC heating. I doesn` t have a multi-turn (precision) 50 Ohms/2W pot, and I used the circuit on Fig. 2c. It has some advantage that current flows mostly through R1 and R2, and not through (possible problematic) center-wiper contact. We have «fine» adjustment, Fig. 2d. Now we can calculate the cathode resistor. With $U_{ak} = 350V$ and $I_a = I_k = 80mA$, we have about $U_{gk} = -70V$. Then, by Ohm`s Law: $R_k = U_k / I_k = 70 / 0,08 = 875$ Ohms. Not a standard value, but we can use the combination, I used 820 Ohms/25W Al-clad chasis mounted resistor and 56 Ohms/1W in a series. If necessary, lower value = higher current, and opposite. Dissipation in Rk is $P_{rk} = I_k^2 * R_k = U_k * I_k = U_k^2 * I_k = 5,6W$ – we must use at least 10W resistor here. Calculating the cathode bypass capacitor Ck: We want Ck to «bypass» all AC frequencies of interest, intuitively – we need f-3dB at about 1-2 Hz. But:- Power bandwidth f-3dB of our OPT is about 20Hz, and there is not much sense in amplifying the subsonic frequencies that can saturate the core- We need not too large RC time constant here – quick bias «recovering» from overloads- For say, 2Hz –3dB high pass frequency we`d need large and expensive film cap, or electrolytic (hmmm...) Then, I choose low-cut frequency around 5-10 Hz. Let`s see: Our Ck «see» the cathode impedance $Z_k = (r_p + R_a) / (\mu + 1)$ in parallel with cathode resistor Rk, or $R_{cath} = Z_k // R_k$. The formula for $C_k = 1 / (2\pi * f * R_{cath})$, and when we put those equations together, we get the final formula for cathode capacitor: $C_k = [(\mu + 1) / (r_p + R_a) + 1 / R_k] / 2\pi * f$, or obviously f-3dB is: $f-3 = [(\mu + 1) / (r_p + R_a) + 1 / R_k] / 2\pi * C_k$ When we put some numbers in it, and use the standard 47µF/100V MKP cap here, we get f-3dB about 8,4 Hz: $f-3 = [(3,85 + 1) / (650 + 3000) + 1 / 875] / 2 * 3,141 * 47 * 10^{-6} = 8,4$ Hz Note that we use $R_a = 3000$ Ohms, like constant resistance value, but our OPT is far from that, we neglected L_p , R_w , etc. But, possible mistake is small, and can be neglected for our purposes. The quality of Ck is critical, and it`s recommended that we use quality film cap here. And not just that, see Fig. 3 – SE stage «redrawn» to include PS capacitor(s). We can see that both Ck and Cps are inside the output signal current loop, and that both caps are practically in a series. Then, quality of Cps is also critical, and it can also be MKP or MKV types. In Fig. 4 we can see the final SE stage, with all the values. I choose the «safe» value for grid-stop resistor $R_{gs} = 1k$, non-inductive type (say, carbon-comp), mounted close to the tube pin. For grid resistor Rg, we need small value from the output tube standpoint, and large value from the driver tube standpoint. Some people put grid-choke here (rel. small DC resistance and large AC impedance), but we`ll use «standard» 220k here, somewhat smaller than max. recommended 250k from 300B data. I choose 0,22µF for coupling capacitor Ci (between the driver tube and output stage). We have the first order high-pass filter here, 6dB/octave. Again, we need «low enough» -3dB high pass point, but not too large RC time constant, because of possible «blocking» effect. Again, the quality of this capacitor is critical. Combination of 220k/0,22µ gives: $f-3 = 1 / (2\pi * R_g * C_i) = 1 / (2 * 3,141 * 220000 * 0,22 * 10^{-6}) = 3,3$ Hz. The formula for $C_i = 1 / (2\pi * f * R_g)$, obviously :-). We have another «unpleasant» effect with our output stage, the input capacitance: $C_{in} = C_{miller} + C_{gf} + C_{strays} = (A + 1) * C_{ag} + C_{gf} + C_{strays}$. From Parts 1&2 we know that amplification of our output stage is output AC signal swing divided with input AC signal swing, or $A = U_a / U_{gk} = 3$. Then

we have: $C_{in} = (3+1)*15 + 9 + 11 = 80\text{pF}$. Values for C_{ga} and C_{gf} we have in 300B data, and value for C_{str} we estimated. Now, with 80pF of input capacitance and at least 100kHz driver bandwidth, our output resistance R_{out} from the driver can be the maximum $R_{out} = 1/(2\pi*f*C_{in}) = 1/(2*3,141*100000*80*10^{-12}) = 19,9\text{k}\Omega$. Although for «driving» $Z_{cin} = 1 / 2*\pi*f*C_{in} = 99,5\text{ k}\Omega$ on 20 kHz with full input signal of 49,5Vrms requires just $I=U_{gk}/Z_{cin}= 0,5\text{mA}$ of AC driver signal current, we need driver that «works» with at least a few times that current, to avoid so called «slewing» distortion. In Fig. 5 we can see the possible wiring of our output stage. C_k can't be too close to the hot R_k . Of course, the designing methods here are «shortened» and simplified, and some designing choices are subjective. But, I hope that DIY-ers can have some «basis» in above, for understanding and experimenting with SE stages...

Subject: my favourite part....

Posted by [PakProtector](#) on Sun, 30 Oct 2005 20:50:56 GMT

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Hey-Hey!!!, You mention the 300B grid requiring a max of 0,5 mA. This is all very well and good. No issues with the math. The critical thing is to look at what delivering that current from a non-zero output Z would be. If we take a 5687, with its output Z of ~3k, that 0,5 ma is going to create a 1.5V drop across it. Not a large fraction indeed. Take a 6SN7 with an unbiased cathode R of 1k, and plate Z becomes $R_p + (u+1)R_k$. If we take R_p of 7k, and u to be 17, we are going to wind up with an output Z of 7k + 18k or 25k Ω ...with 0,5 mA, this drops 12,5 V...a lot more than our 5687 example. cheers, Douglas

Subject: Re: my favourite part....

Posted by [Damir](#) on Mon, 31 Oct 2005 17:42:13 GMT

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Good point, thanks. I had a plan to write something about driver(s) issues in the next "chapter(s)"... BTW, I found a typing mistake, the correct formula (obviously) for cathode resistor dissipation is $P_{rk} = U_k^2 / R_k$.
